

## Al aided inspection of a free-form high-gloss polymer part

COMET Competence Centers for Excellent Technologies





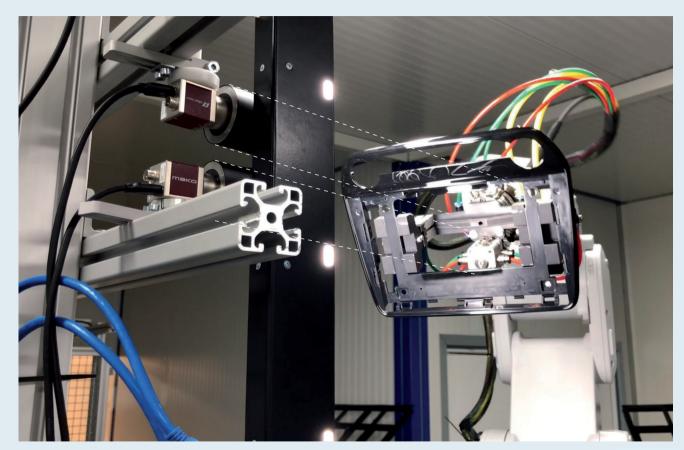


## The aim of the project

The objective of the project was a new defect inspection system that enables an **inspection of the entire component surface**within the production cycle time.

It was necessary to carry out a full surface inspection **within 10 seconds**.





Experimental PCCL inspection robot in cooperation with Flextronics International kft at the site in Sarvar (Hungary)

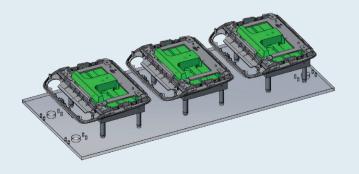


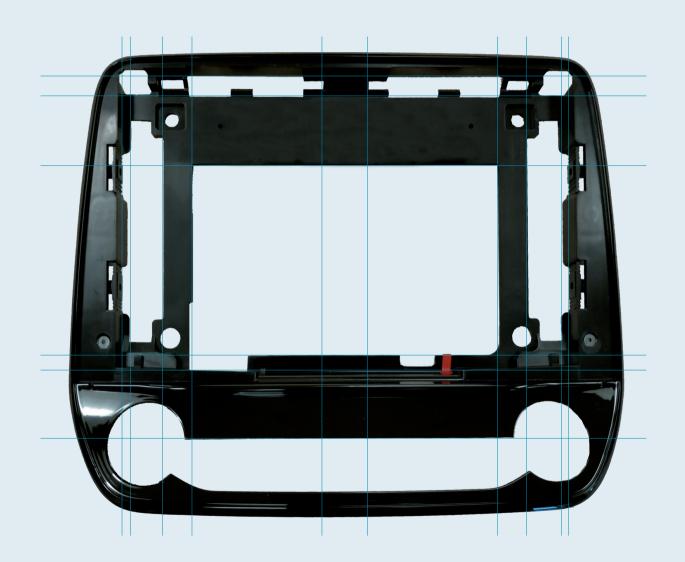


# Attributes of the inspected part

The part has a complex shape and a **free-form surface**.

It is **high-gloss** and **painted black**, which makes its automatic inspection unique and challenging.





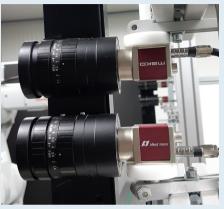


### The inspection system

The automated optical inspection system demonstrator consists of **three cells**, each equipped with a **deep learning pipeline** developed by PCCL, used to detect and classify the surface defects.

The system uses **industrial robots** for picking and handling the parts during the inspection.







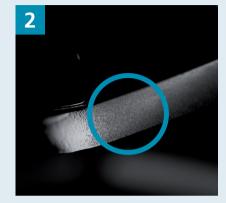


# Detectable defect types

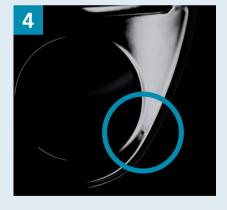
Currently, the 3D-shaped components are tested for 6 different defects (can be extended).

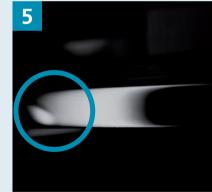
- 1 Craters
- Foggy areas
- Orange skin effects
- 4 Paint dots
- 5 Paint flows
- **6** Scratches







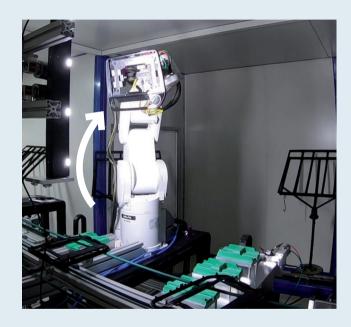




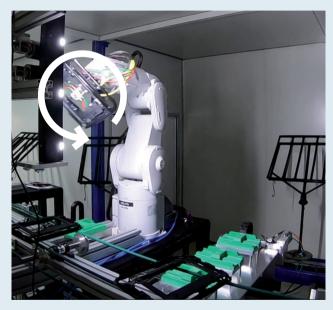




## The procedure



The robots grab the parts from the trays.



The robots perform the full surface inspection in 10 seconds.



The parts are put back (OK part), or are sent to scrap (NOK).

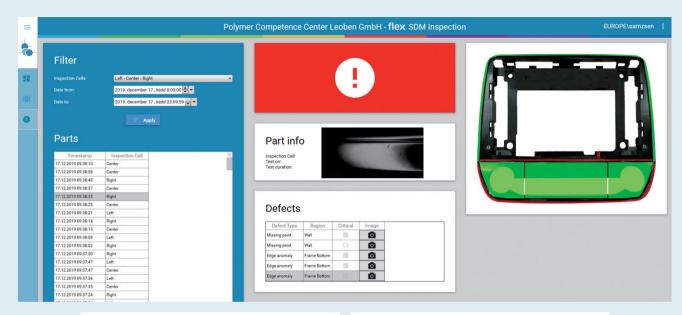


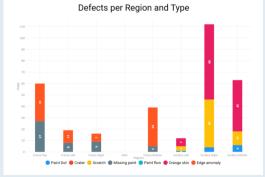
#### The GUI

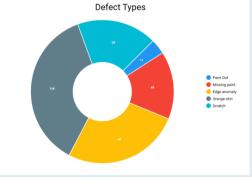
The graphical user interface (GUI) of the inspection system is **comprehensive and user friendly**.

After inspection of each part, **images** of the detected defects can be viewed on the GUI.

**Statistics** provided by the system (e.g. region of the defect, robot number, criticality of the defect) can point out **recent problems** on the production line.









### System advantages

- Full inspection within the cycle time of the production of the part is possible (~10 seconds).
- The system can be integrated into the production line.
- Inspection is fast, robust and reliable. Its performance is more accurate than that of human inspectors.
- The system is flexible, new de- fect types can also be added for detection and classification.
- The system can be extended to inspect other similar parts.







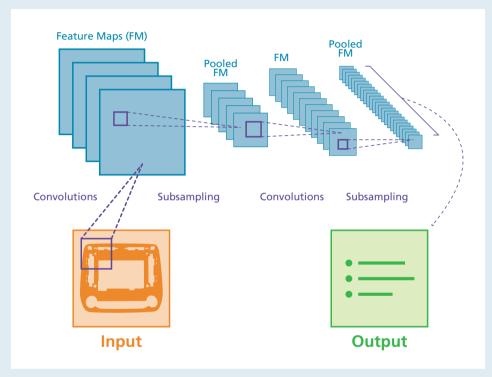


### Speed and adaptability

Image acquisition and image analysis are fully **parallelized**.

This allows the system to detect all defects **within the cycle time** of the production line.

The inspection software uses multiple independent neural networks responsible for different regions and defect types. When characteristics of a defect change, a single neural network can be re-trained without affecting the performance of the rest of the system.



Basic functionality of a convolutional neural network



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#### **Awards**











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#### Partners

















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